



# SOLUTION

## **FLW** *ENSIS*

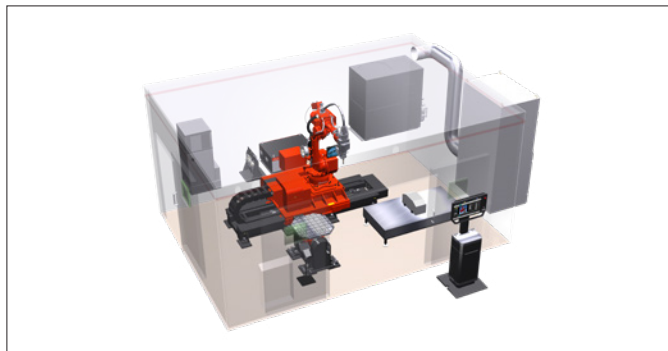
HIGHER OUTPUT WITH LESS SETUP



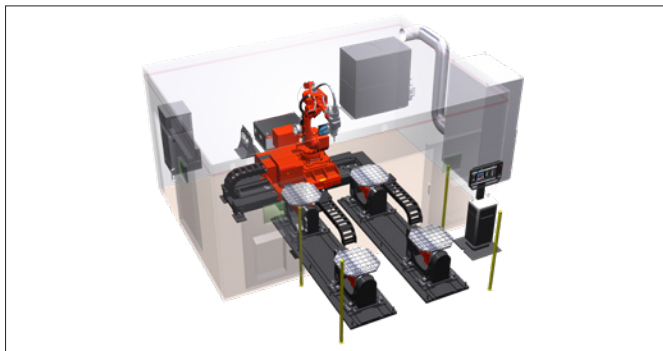
## HIGHER OUTPUT WITH LESS SETUP

Utilizing AMADA's original Variable Beam Control technology in either 3kW or 6kW variants, the FLW-ENSIS<sub>Se</sub> allows a wider range of welding applications to be covered. The new AI-TAS function automatically detects welding positions and corrects the robot position as necessary. Other standard features such as the automatic Push-Pull filler wire function and automatic focal point adjustment aim to provide high quality parts with reduced setup.

**M3 - Robot carriage, fixed positioner table**



**M5 - Robot carriage, 2 exchange tables**



### MAIN FEATURES

- ENSIS technology (Variable Beam Control)
- 3kW or 6kW welding power options
- AI -TAS (Teaching Assist System)
- Multiple positioner table options
- Automatic Push-Pull filler wire function
- AMNC 4ie control
- Beam Weaving

### BENEFITS

- Wider range of welding applications can be covered
- High speed, deeper penetration possibilities
- Artificial Intelligence for faster setup
- System layout to suit your production requirements
- Large gap welding with Push-Pull filler wire management and control
- Facial recognition for personalized operator setup
- Assist large gap welding

### MACHINE SPECIFICATIONS

| FLW-3000ENSIS <sub>Se</sub> |                                 |       | M3                                                | M5    |
|-----------------------------|---------------------------------|-------|---------------------------------------------------|-------|
| Numerical control           |                                 |       | AMNC 4ie                                          |       |
| Operator protection         |                                 |       | Full cover partition (safety level T2)            |       |
| Carriage                    | Travel stroke                   | m     | 3                                                 | 4     |
|                             | Maximum travel speed            | m/min | 60                                                |       |
|                             | Repeatable positioning accuracy | mm    | ± 0.1                                             |       |
| Positioner table            | Maximum payload capacity        | kg    | 500                                               |       |
|                             | Rotating axis                   |       | ±720°                                             | ±200° |
|                             | Tilting axis                    |       | ±90°                                              |       |
|                             | Maximum travel speed            | m/min | -                                                 | 30    |
| Cabin dimensions*           | L x W x H                       | mm    | Dependent on work type and customer requirements. |       |

### OSCILLATOR SPECIFICATIONS

|                 |   | ENSIS-3000                          | ENSIS-6000 |
|-----------------|---|-------------------------------------|------------|
| Beam generation |   | Laser diode excitation, fibre laser |            |
| Maximum power   | W | 3000                                | 6000       |
| Processing head |   | AMADA                               |            |

### ROBOT

| MC2000           |                                   |
|------------------|-----------------------------------|
| Robot            | Vertical articulated 6-axis robot |
| Robot controller | YRC1000                           |

\* Please refer to your specific layout drawing.

Specifications, appearance and equipment are subject to change without notice by reason of improvement.

Hazard prevention measures are removed in the photos used in this sheet.

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